

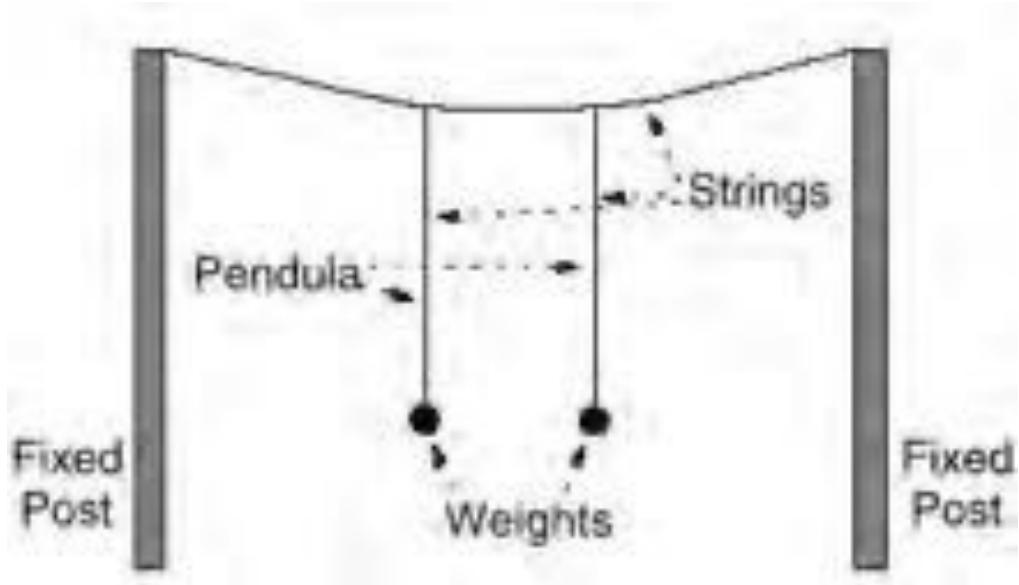
A – lab NEMS



Advanced NEMS Lab Lab projects

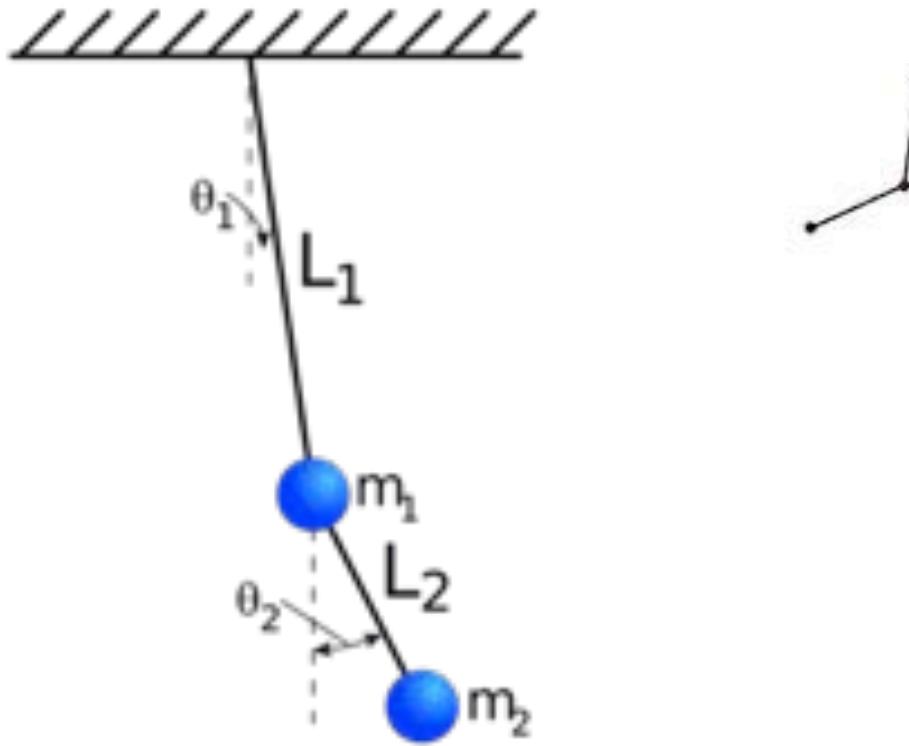
- Sync - Systèmes couplés
- Pendule Double - Système chaotique
- Boîte d'isolation acoustique

EPFL Projet 1 - Synchronisation



- Qu'est-ce qu'on va faire?
 - Design & Fabrication d'un système de résonateurs couplés
 - On mettra sur place la démonstration de synchronisation

EPFL Projet 2 – Pendule Double (ou triple ☺)



- Qu'est-ce qu'on va faire?
 - Étude Analytique du système
 - App pour modéliser le système
 - Design & Fabrication d'un système physique
 - On mettra sur place la démonstration

EPFL Projet 3 – Boîte d'isolation acoustique



- Qu'est-ce qu'on va faire?
 - Étude du design et des matériaux
 - Important – en gardant (peut-être un air flow)
 - Design & Fabrication de la boîte



- Mercredi prochain
 - 15.12
 - Polydôme
 - 14-16h (série d'exos de Mec Vibra)

- By email:
 - Guillermo.Villanueva@epfl.ch

B – Egg drop challenge



The Egg Drop Challenge

Tobias M. Schneider (ECPS)
Guillermo Villanueva (NEMS)

SpaceX Crew Dragon splashdown



Challenge: Protect sensitive 'cargo' on impact... using structures of minimal weight

Challenge: Protect an egg when dropping it

Task: Construct device protecting raw egg for maximum drop height
given specified constraints (weight, materials, active components,....)

Examples:



The competition

- Given constraints (weight,)
- Find an optimal solution in groups of 3
 - Approach: dampers / ~~parachutes~~
 - Material choices / structures
 - Back-of-the-envelope calculations / physical reasoning – when does the egg break?
 - Simulations
 - Experiments / Tests
- Competition:
 - Minimum weight of protective structure to survive a drop from BM 6th floor
- Constraints:
 - Lighter than XX grams (XX to be defined)





- Mercredi prochain
 - 15.12
 - Polydôme
 - 14-16h (série d'exos de Mec Vibra)

- By email:
 - Guillermo.Villanueva@epfl.ch

C - UNFold

L'art de la Godille



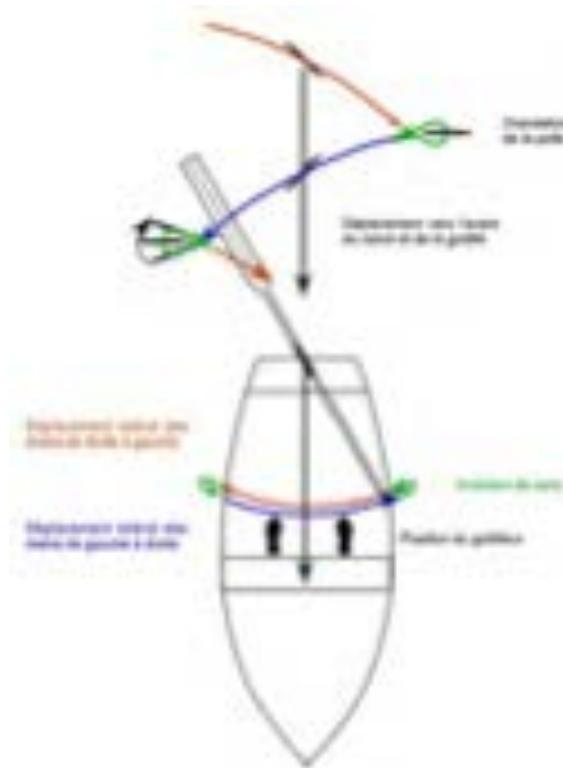
Exposition Iffic, 2018

■ Projet d'Ingénierie Simultanée



France 3 Iroise
[youtube.com/watch?v=C9yVqgCjqT4](https://www.youtube.com/watch?v=C9yVqgCjqT4)

L'art de la Godille



G. Roudaut, *L'art de la godille*



Godille à UNFoLD

L'art de la Godille

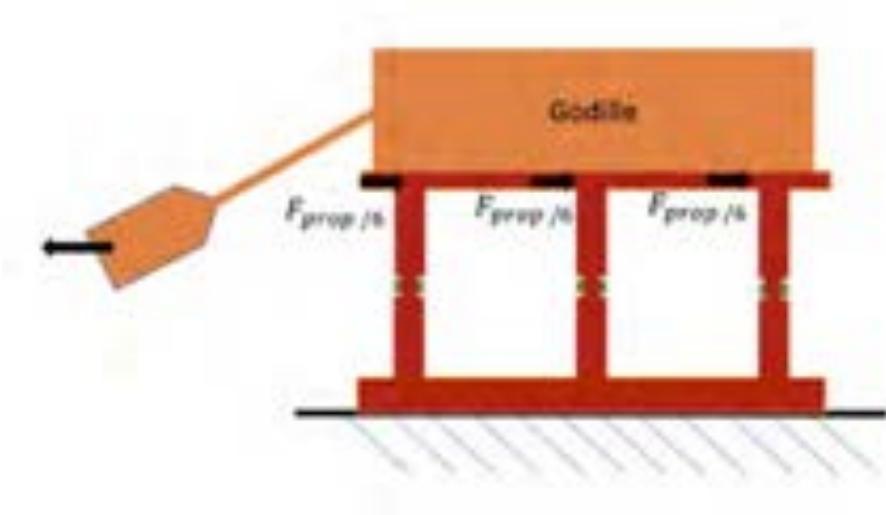
Projet 1 : système de contrôle pour les 2 moteurs

- Limit switch et homing procedure
- Control independent en rotation et en pitch



Projet 2 : plateforme de mesure de forces

- Mesure de la poussée exercée par la Godille dans un bassin
- Calibration et validation



D – Lab LA

Ingénierie simultanée 2022

Laboratoire d'automatique

christophe.salzmann@epfl.ch

Mini Segway challenge

Multi-years challenge

Year 1 : initial mechanical setup + stand up control

Year 2 : path following/tracking + communication

Year 3 : crowd control via camera tracking

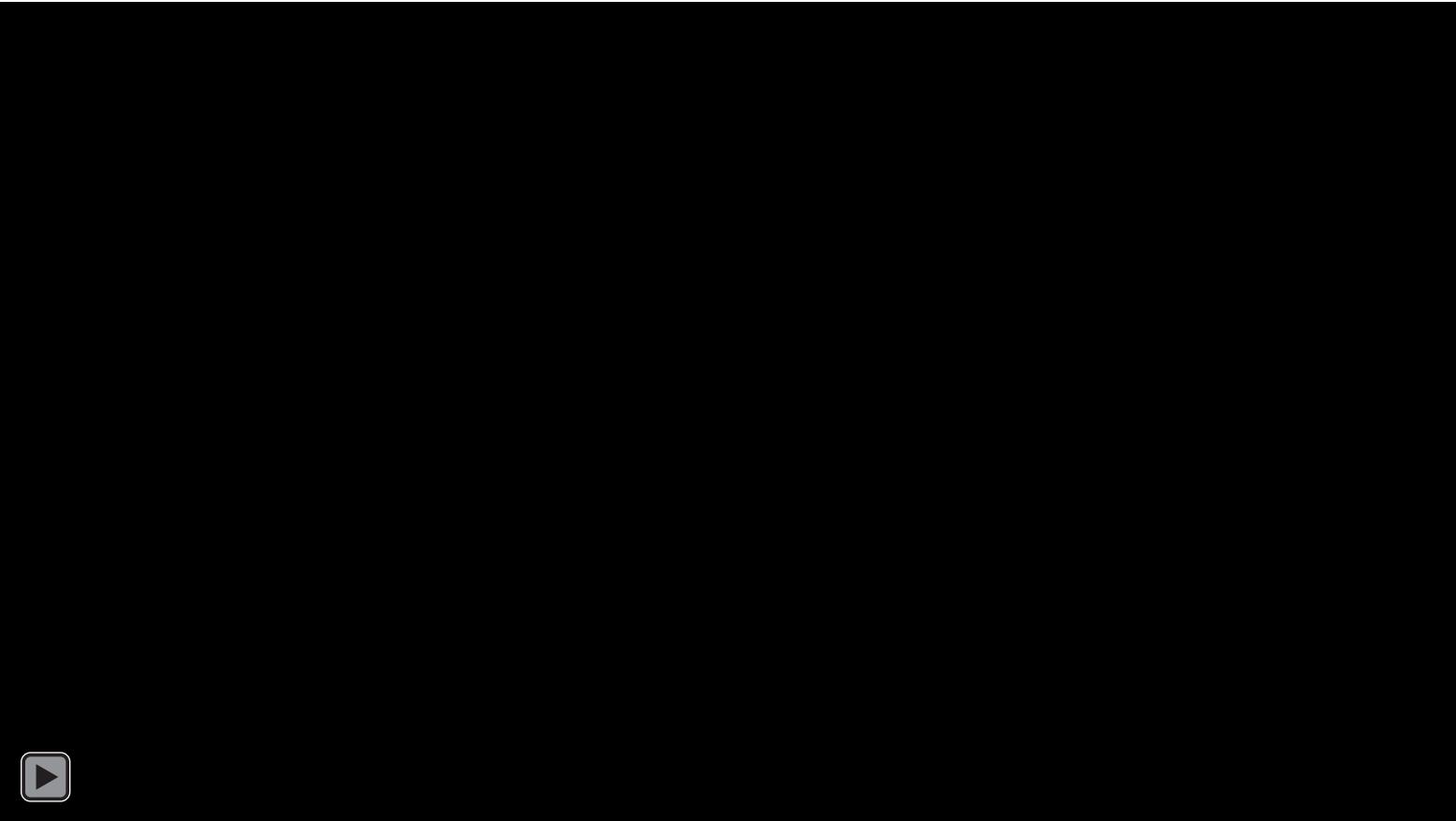


Nbr etudiants: 16

Responsables:

Christophe Salzmann

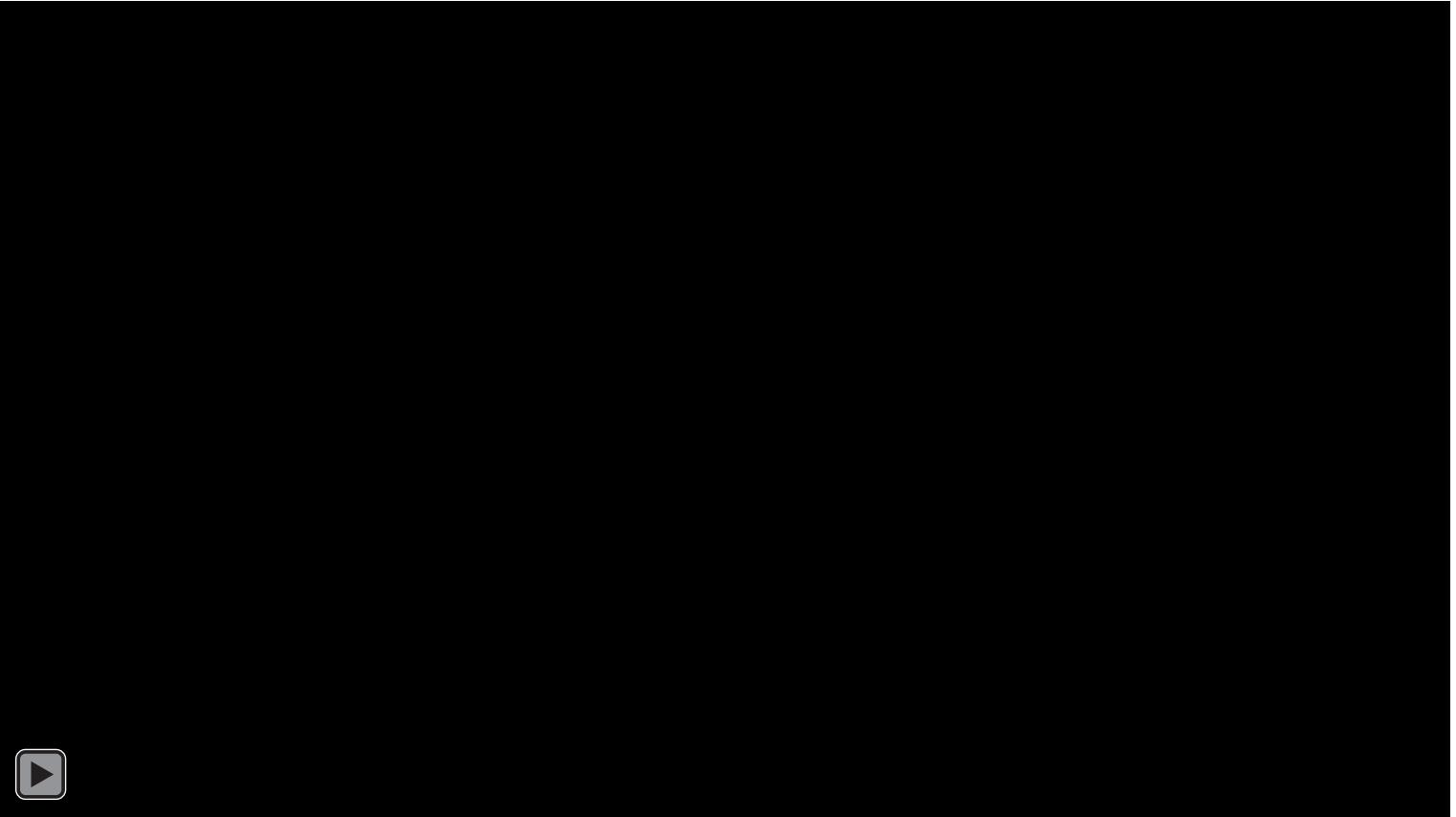
Babyfoot fine control



Improve strategy and tricks
Programmed in LabVIEW !

Nbr etudiants: 2
Responsables: Christophe Salzmann

QUBE Extension(s)

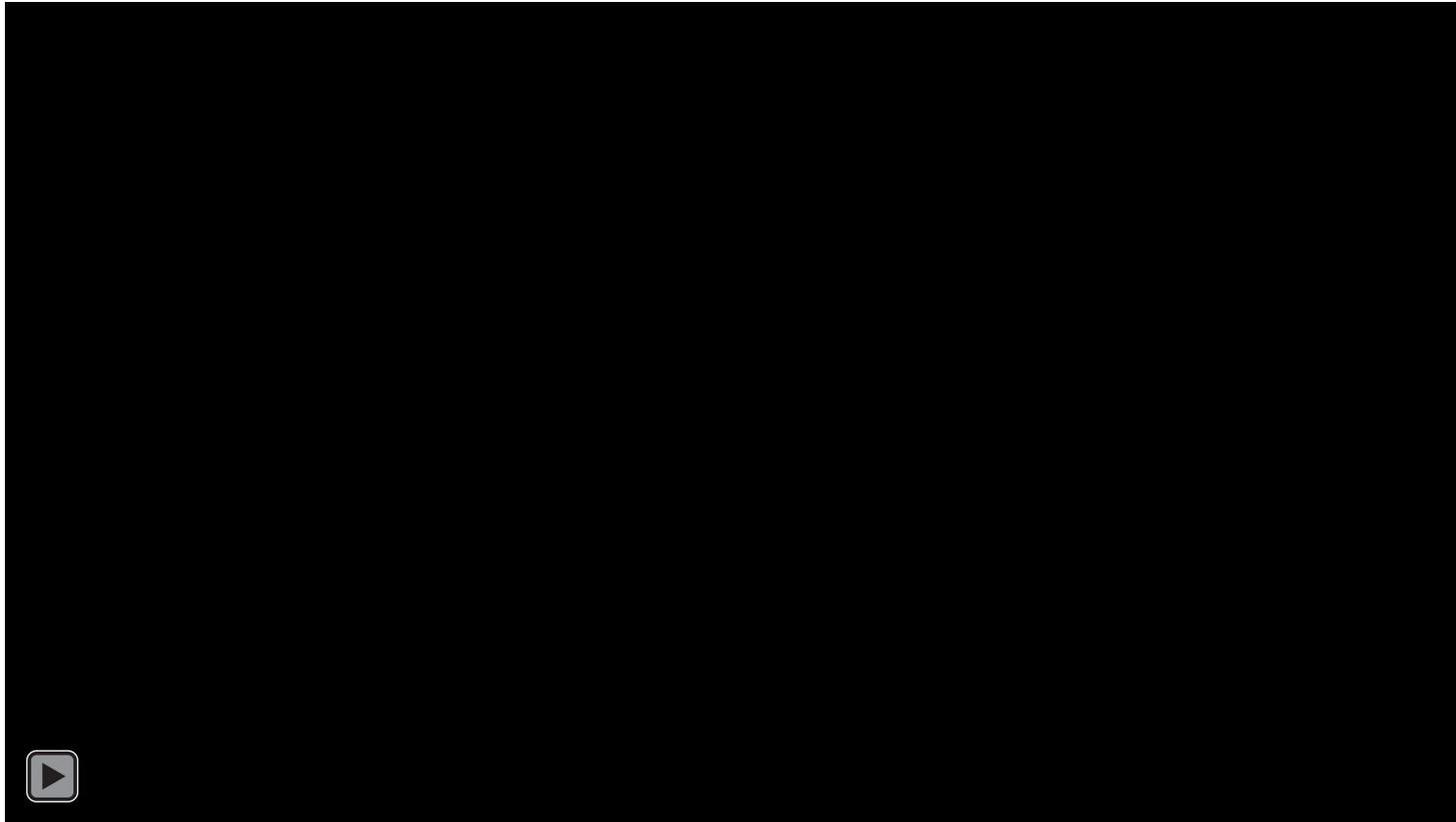


- New support for remote experimentation (cameras, usb, power)
- New extensions for the QUBE
- Design hardware and related controllers

Nbr etudiants: 2

Responsables: Christophe Salzmann

Bouncing table(s) v1 -> v2



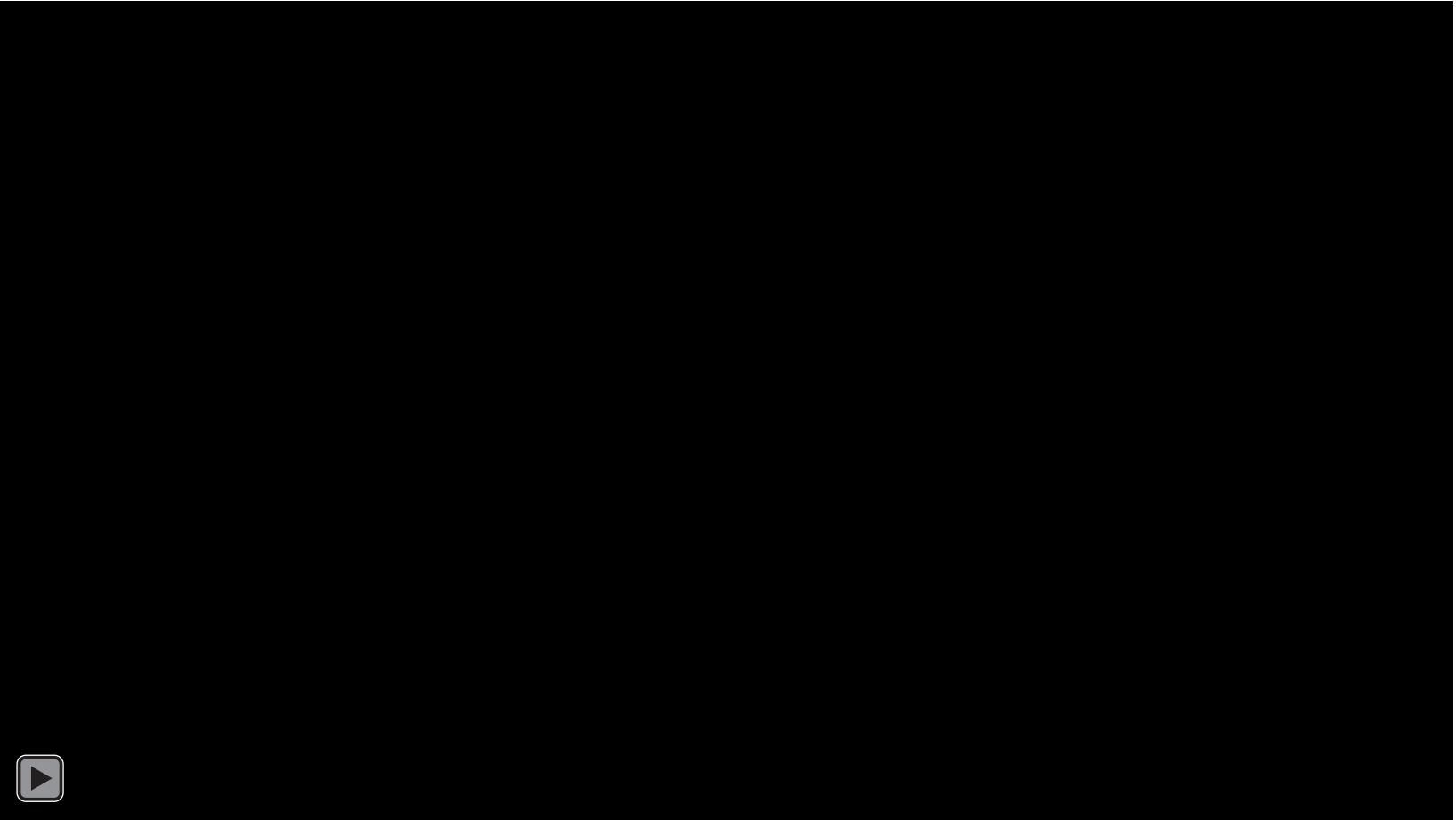
<https://www.youtube.com/watch?v=YYAMDYzJQM>

- Build and control a bouncing table(s)
- Mechanical design
- Controller design
- Vision

Nbr etudiants: 2-4

Final project will bounce between two or more tables

Bouncing table(s) v2



- Build and control a bouncing table(s)
- Mechanical design
- Controller design
- Vision

Nbr etudiants: 2-4

Final project will bounce between two or more tables

E - Biomobile



Association biomobile

Présentation EPFL - Projets d'ingénierie simultanée

Mission:

Réalisation de véhicules **maximisant** le recours aux ressources

renouvelables:

- Utilisation de **matériaux végétaux** pour la structure de la voiture
(fibre de lin, époxy biosourcée, bois,...).
- Propulsion à l'aide de **carburants** issus de déchets organiques.

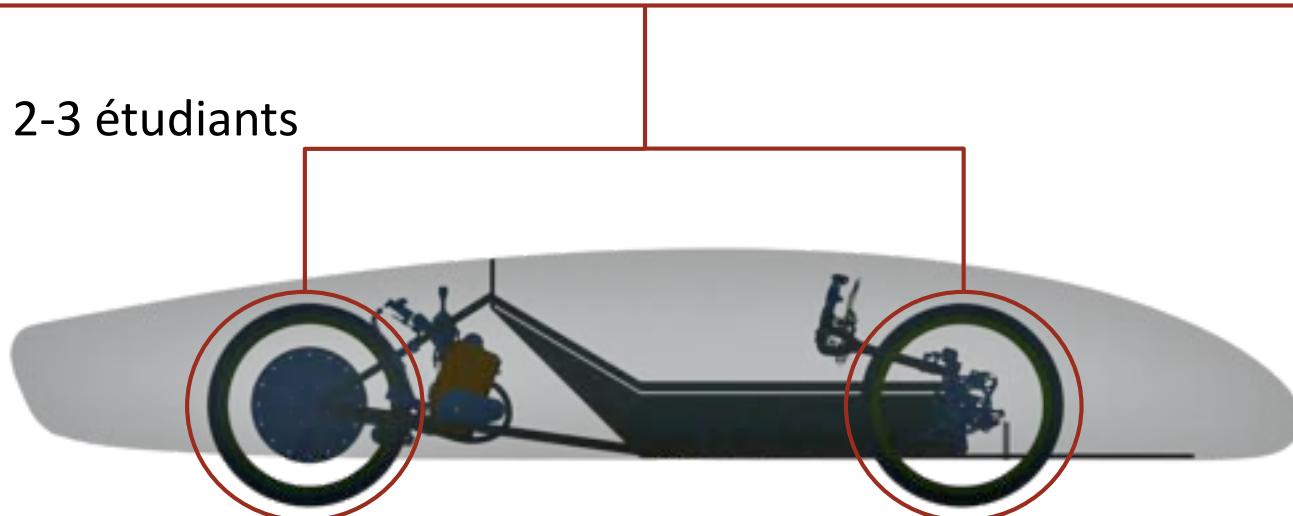
Participer à la **formation** d'étudiants par l'intermédiaire de **projets**
multidisciplinaires, motivants et novateurs.



Projet : Conception innovante des roues

L'objectif : A partir d'un cerclage réalisé en fibre de lin, concevoir les moyeux et un système d'accroche des rayons basé sur l'utilisation de fils.

- Etape 1: Etablir les **cas de chargements** et déterminer les efforts en jeux.
 - Etape 2: **Concevoir** plusieurs solutions et établir le **dossier de fabrication**
 - Etape 3: **Tests mécaniques**, analyses et **choix de la solution**
-
- Effectif: 2-3 étudiants



Plus d'informations sur notre site :

www.biomobile.ch

Adresses de contact :

perraudin@biomobile.ch

coordination@biomobile.ch

022 546 24 56



F - Create

Service Robot Competition - RoboCup @Home

CREATE Lab

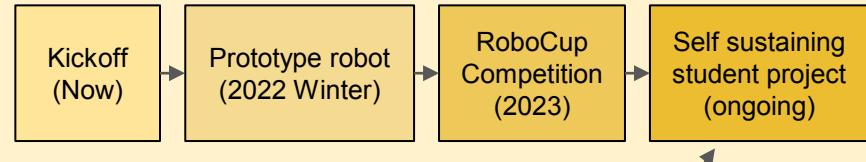
What is RoboCup @Home?



<https://historyofai.files.wordpress.com/2014/04/home5.jpg>

- Annual international competition
- Testing service robots in real life situations
 - Interact with humans (voice commands)
 - Navigation in a room
 - Manipulation of objects

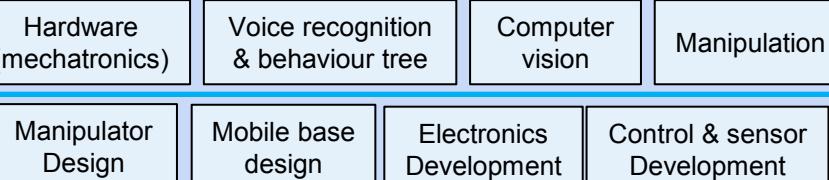
About the project - Long term



Similar to: Swiss solar boat, Xplore, etc...

About the project - next semester

- Develop the robot platform (fresh start)
- Initial testing of control/sensing
- Prototyping (software and hardware)



Who we are looking for

Bachelor project

- Application of theoretical mechanical engineering to a real world problem
- Interest in developing robotic systems
- Want to learn and work on a technical integration project
- Potential interest in continuing this project after the next semester

General recruitment

- Someone keen to take a leadership position (next two years)

Contact kai.junge@epfl.ch

G – FlexLab challenge

Fabrics, Sewing, and Embroidery

SGM - Projet d'ingénierie simultanée 2021-2022

Design goal: You will be ideating, developing, prototyping and exploring an innovative technique, process, structure, application, or a research question that addresses an existing niche in sewn or embroidered fabrics.

Up to 5 teams of up to 5 students. Open-ended project. Lab work will take place at new DLL.

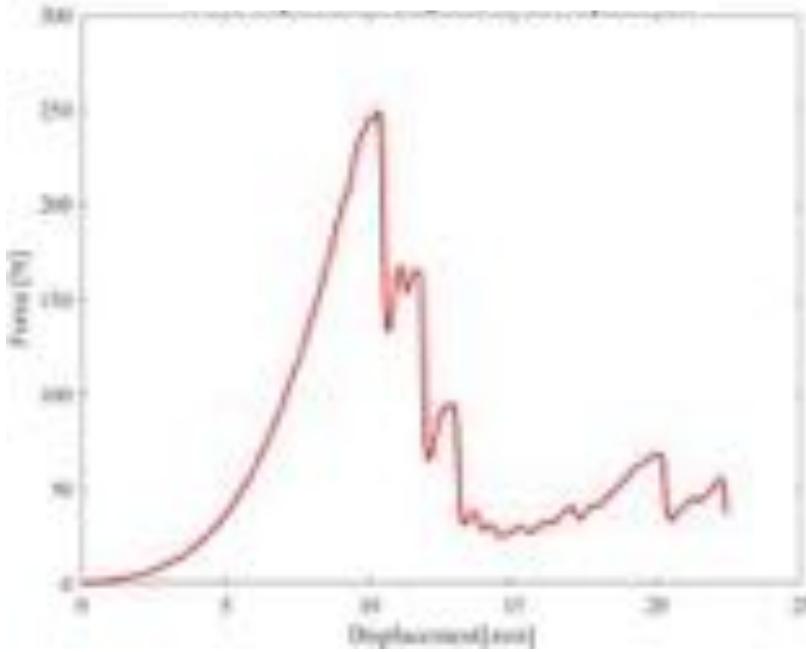
Flexible Structures Laboratory – IGM. Contact: pedro.reis@epfl.ch



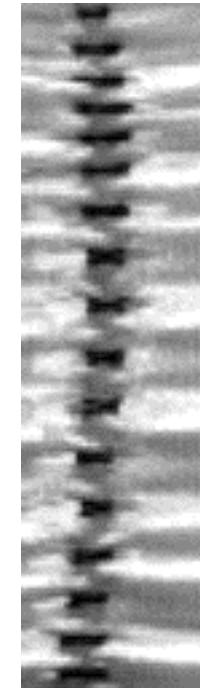
Who cares?

- The fashion industry uses 93 billion m³/year of water; consumption needs of 5M people.
- ~ 20 % of wastewater worldwide comes from fabric dyeing and treatment.
- Of the total fiber input used for clothing, 87 % is incinerated or disposed of in a landfill.
- **The fashion industry is responsible for 10 % of annual global carbon emissions, more than all international flights and maritime shipping combined.**
- If demographic and lifestyle patterns continue as they are now, global consumption of apparel will rise from 62 million metric tons in 2019 to 102 million tons in 10 years.
- Every year a half a million tons of plastic microfibers are dumped into the ocean, the equivalent of 50 billion plastic bottles. The danger? Microfibers cannot be extracted from the water and they can spread throughout the food chain.

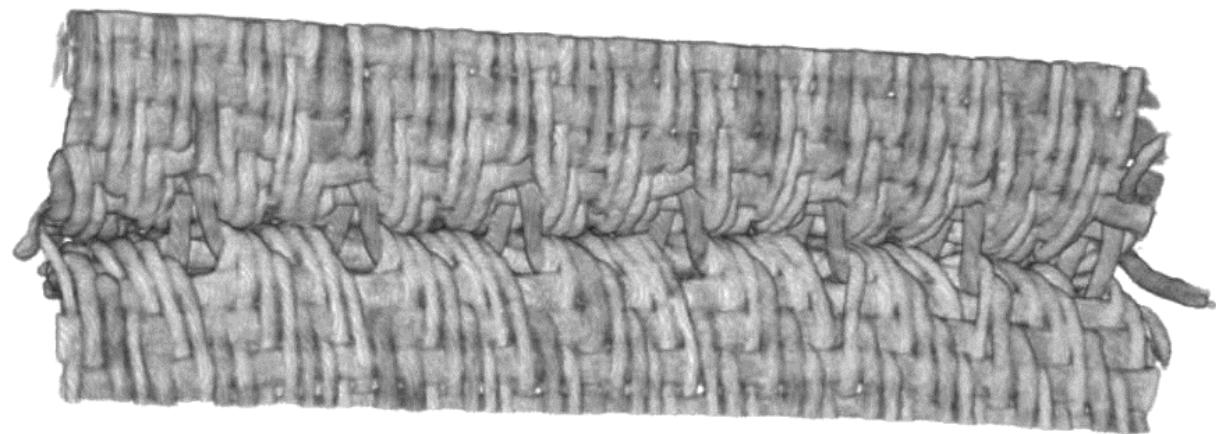
Mechanical testing



40k fps



Innovative imaging (X-ray µCT)



Smart fabrics

In collaboration with

BERNINA
made to create

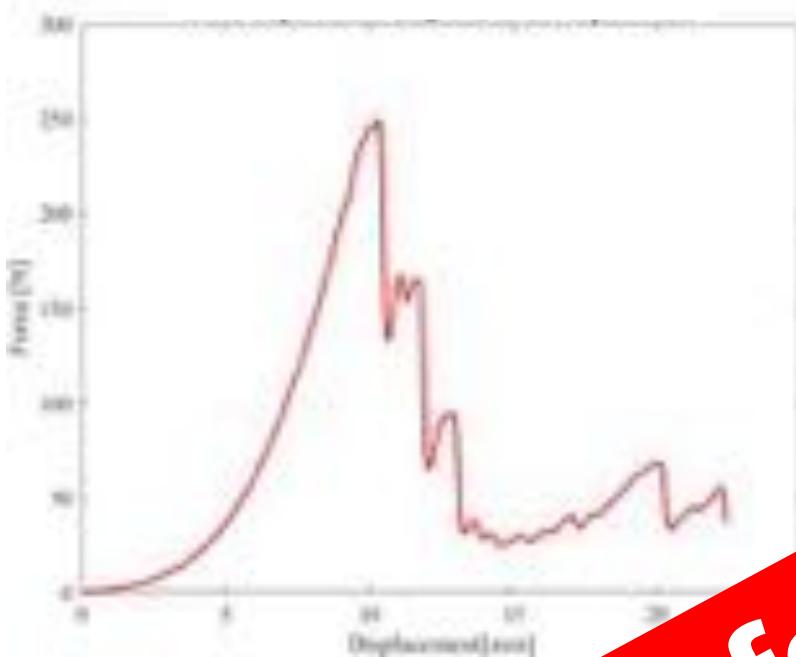


Amann Silver-tech conducting thread

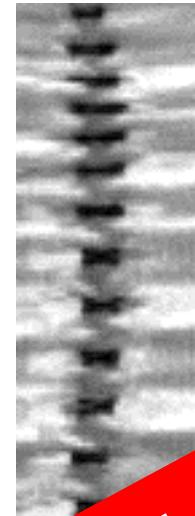


<https://www.youtube.com/watch?v=qiTmaCds2P4>

Mechanical testing



40k fps



Innovative imaging (X)



Smart fabrics



In collabora

RE



Amann Silver-tech conducting thread

<https://www.youtube.com/watch?v=qiTmaCds2P4>

Anything fabrics-related is game
for your design/research project

H – Solar Boat



Swiss Solar Boat



Swiss Solar Boat

Projet d'ingénierie simultanée

Objectifs



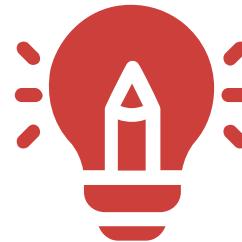
Renforcer
l'apprentissage



Partager une
aventure humaine



Sensibiliser aux
énergies vertes



Proposer un
concept innovant



S'inscrire comme
un challenger
sérieux



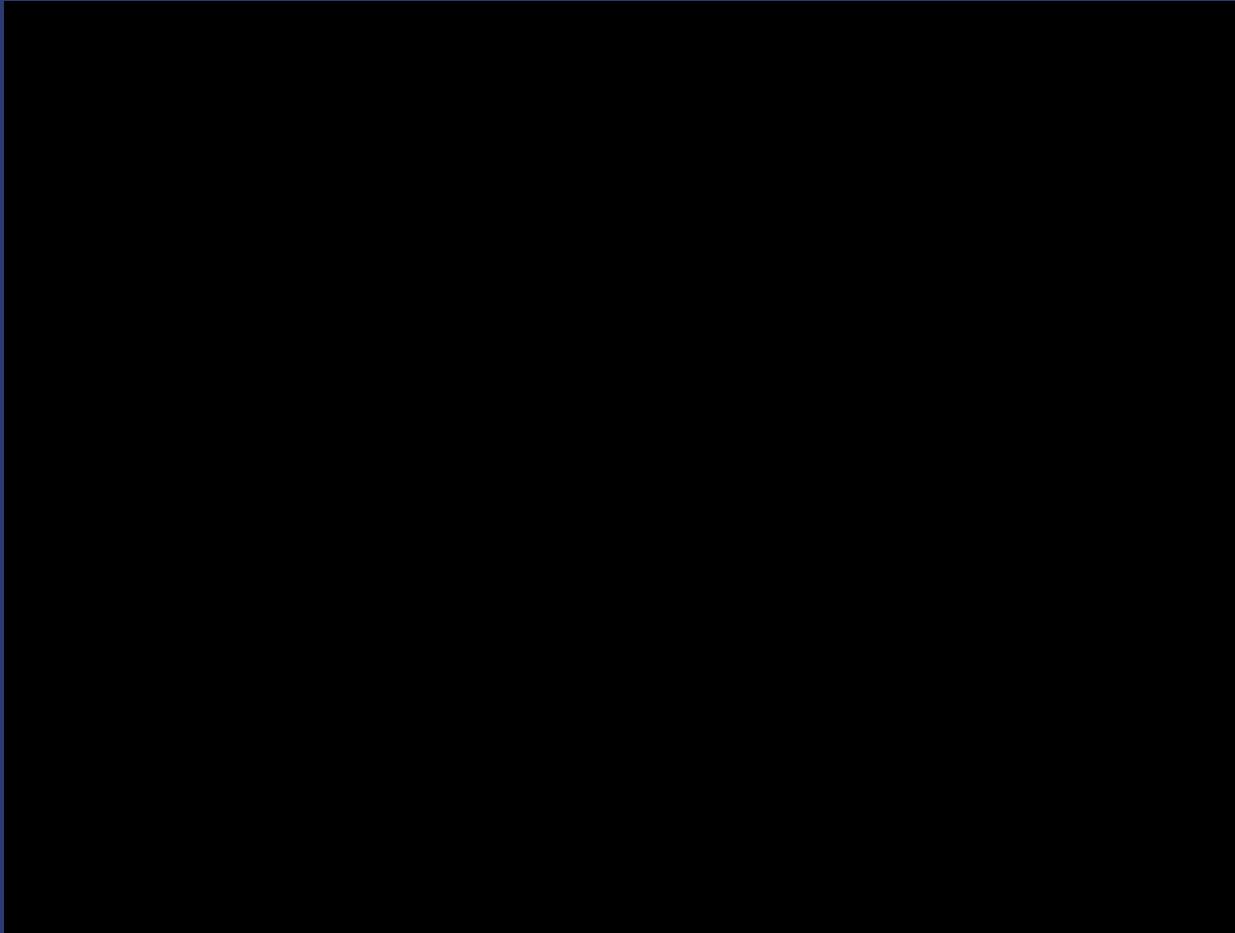


Monaco Energy Boat Challenge



- Compétition entre étudiants et professionnels organisée par le Yacht Club de Monaco
- Participation à la catégorie solaire: un pilote, des panneaux solaires, un design libre
- Partage de connaissances
- Promotion de l'innovation vers des énergies propres





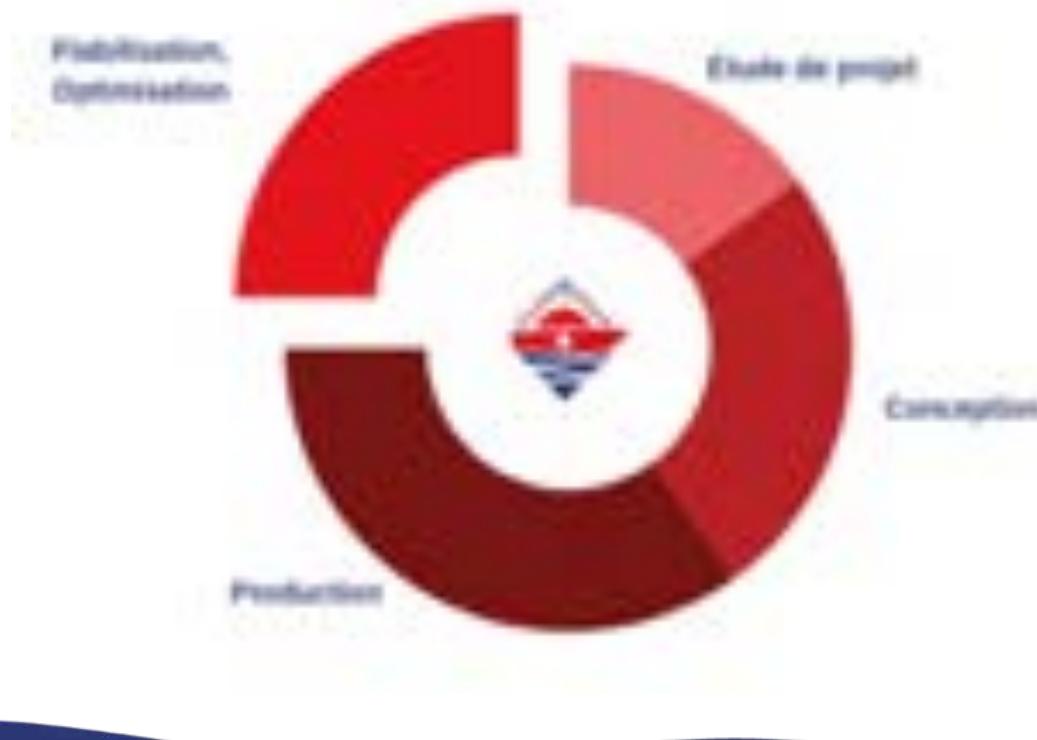
Résultats

- 2^{ème} place
- Prix de l'écoconception



Et après ?

Gestion de projet





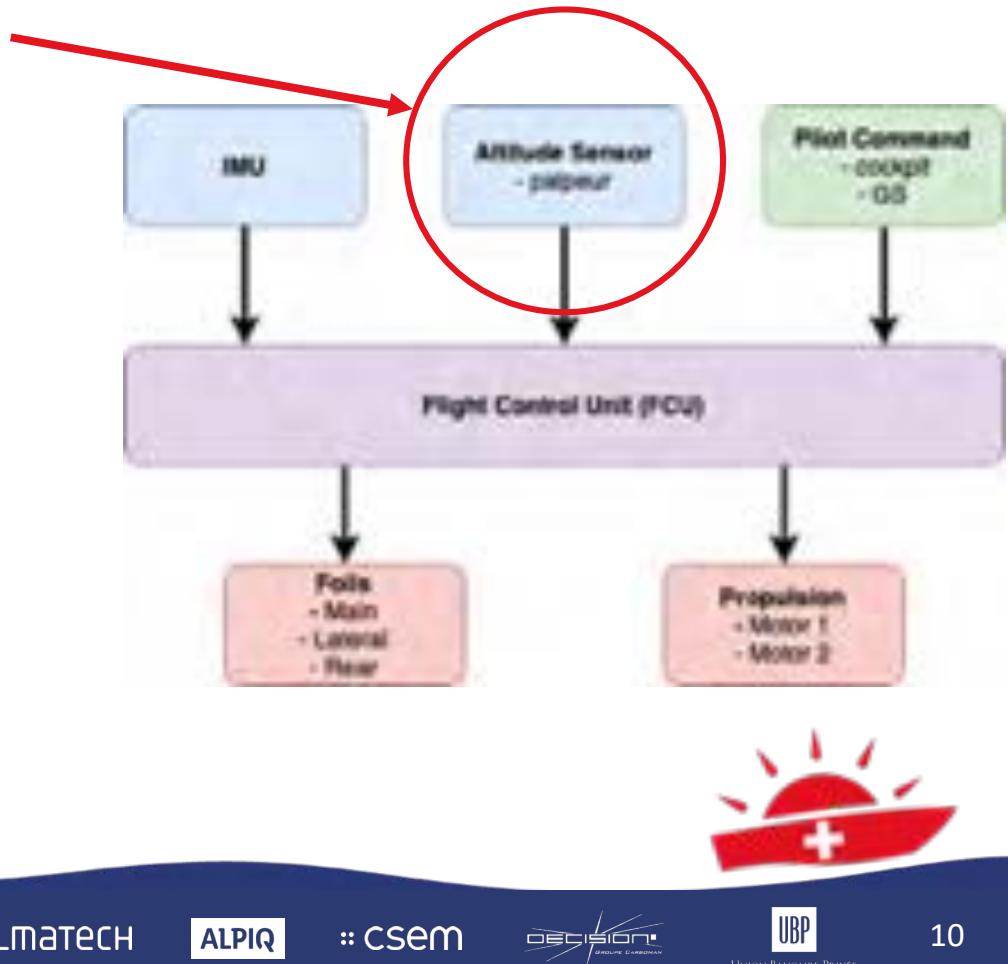
Swiss Solar Boat

Projet 1 : Mesure d'altitude

Projet 1 : Mesure d'altitude

Control du bateau :

- FCU:
 - Board STM32 nucleo
 - Code C/Cpp
 - Programmable à distance (Raspi/USB)
 - Cerveau du bateau
- PIDs controllers
 - Altitude
 - Roll
 - Pitch
- Modèle Numérique du bateau
 - Code Matlab
 - Simuler le comportement du bateau



Projet 1 : Mesure d'altitude



- Actuellement : Palpeur mécanique
- Atout : Fonctionnel et simple
- Désavantage : Sensible aux rebonds, pas très robuste.



Projet 1 : Mesure d'altitude

Objectif du projet :

- Etudier les différentes pistes possibles : capteur Ultrason, Radar, Lidar, Caméra...
- Regarder comment l'implémentation peut se faire en partenariat avec d'autres projets
- Rendre le système robuste : aux marches arrières, aux éclaboussures
- Travailler avec l'objectif de l'efficience et l'écoconception (réduire la consommation et le poid)





Swiss Solar Boat

Projet 2 : Production du CUS

Projet 2 : Production du CUS

Composite Upper Structure



Projet 2 : Production du CUS

- Production de la lower part en fibre de carbone : usinage des moules, préparation des fibres, mise en places des fibres
- Upper part en fibre de lin
- Etanchéité à gérer
- Production doit commencer le plus tôt possible (début février)





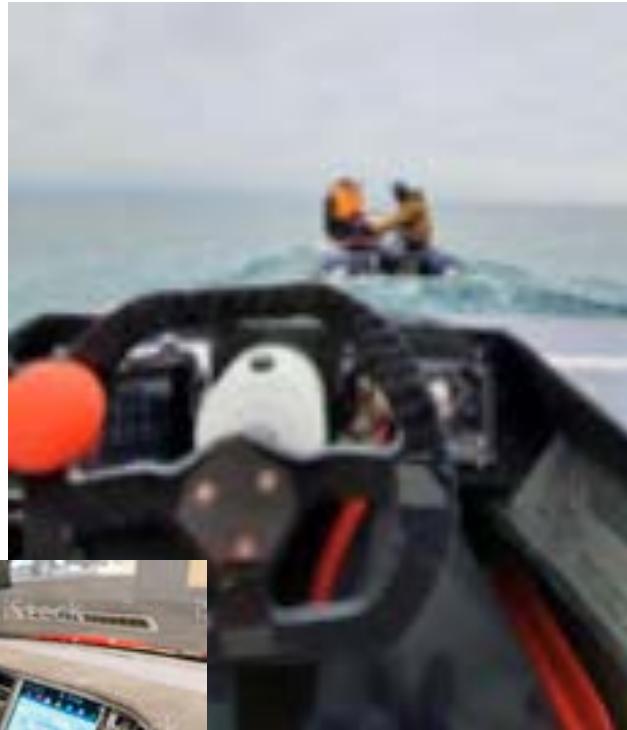
Swiss Solar Boat

Projet 3 : Interaction Pilote bateau

Projet 3 : Interaction Pilote bateau

Objectif du projet

- Améliorer le cockpit actuel : design épuré,
- Refaire volant
- Manche à balais pour les virages
- Ajouter écran type “tesla”
(code Javascript)





Swiss Solar Boat

Projet 4 : Production vertical latéral

Projet 4 : Production vertical latéral



Projet 4 : Production vertical latéral

Objectif du projet

- Produire le vertical latéral en fibre de carbone
- Conçu par les étudiants en master de SSB
- Renforcé par rapport aux verticaux en alu
- Commencer la production au plus tôt
(Janvier/Février)





Swiss Solar Boat

Projet 5 : Production des foils

Projet 5 : Production des foils



Projet 5 : Production des foils

Objectif du projet

- Production des foils V2, V3
- Priorité foil latéral
- Designé par les étudiants en master de SSB
- Commencer la production au plus tôt
(Janvier/Février)



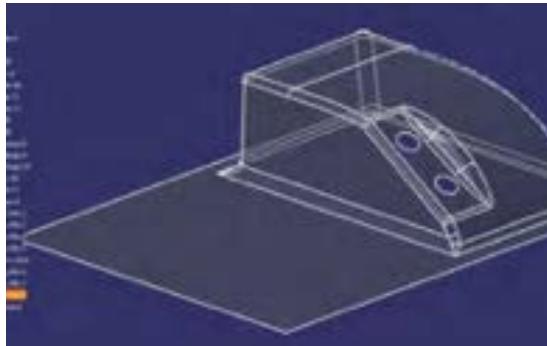


Swiss Solar Boat

Projet 6 : Production de boîtes ultra légères, rack MPPT et capot latéral

Projet 6 : Production des foils

- Production de boîte ultra légère par vacuum forming
- par l'expérience acquise, design V2 du capot latéral
- Design du rack MPPT et production de celui-ci



Bonus



A large group of people, mostly wearing red shirts, are gathered on a long, narrow boat. They appear to be cheering or participating in a race, with many hands raised. The boat has "SOUTHERN CALIFORNIA" printed on its side. In the background, there's a building with large windows and a white pillar. A red rectangular box in the upper right corner contains the text.

Thank you !

I – Duck road trip

Duck Road Trip



Laboratoire d'Automatique
Dependable Control and Decision group
Prof. Giancarlo Ferrari Trecate

Clara Galimberti
Muhammad Zakwan
Mahrokh Ghoddousiboroujeni
Baiwei Guo
Jean-Sébastien Brouillon
Andrea Martin
Liang Xu
Luca Furieri

Duck Road Trip

Objective: Design control algorithms to drive self-driving car around the DuckieTown



Check: <https://www.duckietown.org/>

Duck Road Trip

Learning outcomes:

👉 Teamwork

👉 Coding in Python & understanding existing platform
(DuckieTown)

👉 Implementing control algorithms for tracking, and collision avoidance

👉 Road and object detection from images

Group of 4
students



If interested, don't hesitate to contact us:

Clara Galimberti

– clara.galimberti@epfl.ch 🐥

Muhammad Zakwan

– muhammad.zakwan@epfl.ch 🐥

Mahrokh Ghoddousiboroujeni

– mahrokh.ghoddousiboroujeni@epfl.ch 🐥

Jean-Sébastien Brouillon

– jean-sebastien.brouillon@epfl.ch 🐥

Baiwei Guo

– baiwei.guo@epfl.ch 🐥

Andrea Martin

– andrea.martin@epfl.ch 🐥

J – lab LBO

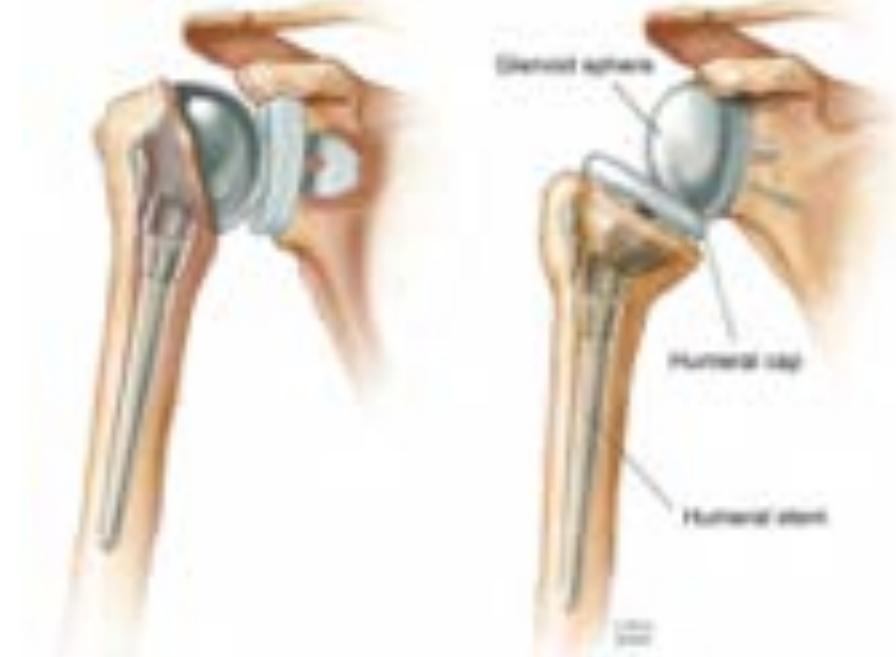
Shoulder Project

Pezhman Eghbali, Laboratory of Biomechanical Orthopedics (EPFL)
Patrick Götti, Service of Orthopedics (CHUV)

- Failure rate of shoulder arthroplasty is mainly associated with mechanical causes
- Preoperative scanner images can be used to build finite element modeling (FEM) to estimate mechanical variables
- Tasks: Use Python coding to automate FEM (Abaqus) from scanner images (with existing triangular mesh)

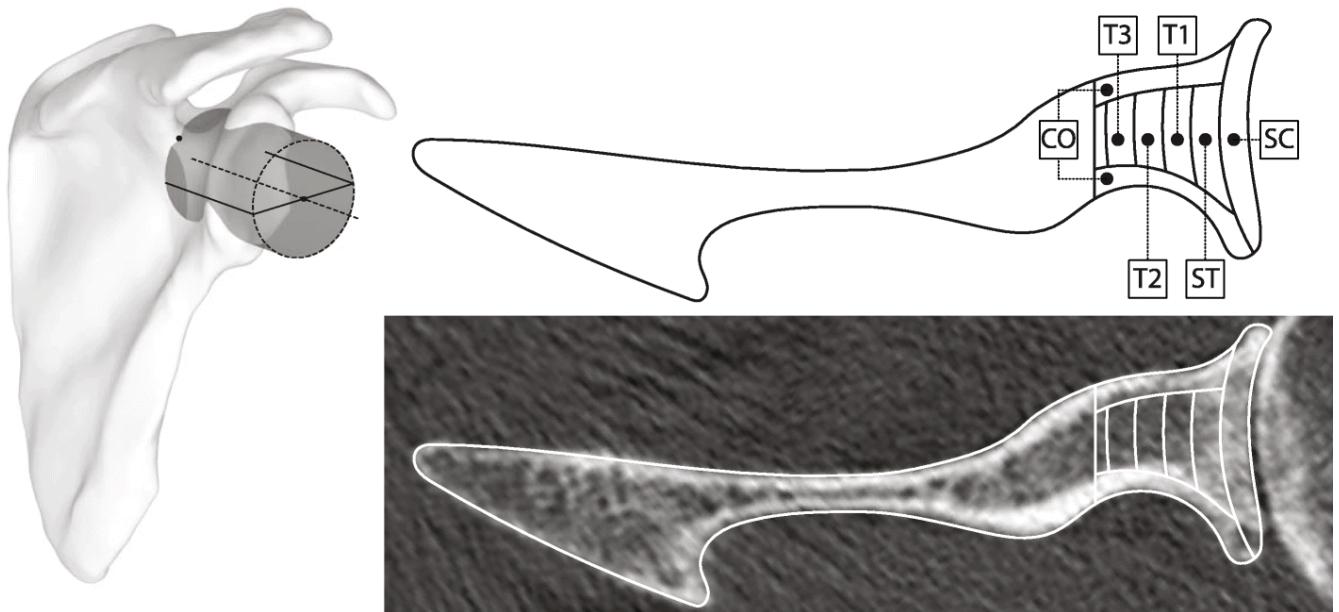
Skills:

- ❖ FE modelling with Abaqus
- ❖ Python Coding



- Bone mineral density (BMD) is associated to bone strength, and several shoulder pathologies (osteoporosis, fracture risk, osteoarthritis)
- BMD can be measured in the glenoid bone and proximal humerus from preoperative scanner images
- Tasks: Detect the cortical and trabecular bone regions in the scanner images using image processing and python coding

Skills:
❖ Python Coding



K – Rocket team



**PROJECT
EPFL ROCKET TEAM**

Design of a small scale
supersonic wind tunnel

Doc-No: 2022_WH_FD_SP_00
Issue: 4
1.0
Date:
Page: 25 Nov. 21
1 of 1

PROJECT PROPOSAL

Title: **Design of a small scale supersonic wind tunnel** Prepared by: Bouwakdh Taha
Project: 2022 EPFL Rocket Team, project Wildhorn Checked by: William Cottier
Filename: 2022_WH_FD_SP_004_SUPERSONIC_WINDTUNNELI
Supervisor: Pr. Noca

Responsible signature

PROJECT DESCRIPTION

The aim of this project is to build a small experimental setup to study flow in the supersonic regime and test imperfections on the rocket body.

The work should focus on designing and building a small scale setup using supersonic air jets produced by pumps to generate the flow and schlieren photography to visualize it and record it for further analysis.

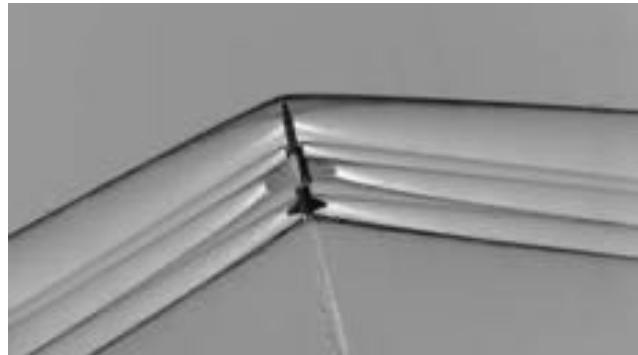


FIGURE 1: Schlieren image displays the shock wave of a supersonic jet (*Credits: NASA Photo*)

Skills needed (or that you are willing to learn):

- Physics: optics.
- Fluid dynamics
- Manufacturing
- Sensors

Contact:

taha.bouwakdh@epfl.ch
kevin.marangi@epfl.ch
supervisor@epfl.ch

Number of students: 3

L – Racing team

Design and Optimization of an in-wheel powertrain system

VD/Powertrain

09/12/2021



Design and Optimization of an in-wheel powertrain system

Function:

- Provide a link between the suspension, the steering, the braking and the tyre
- Transmit engine torque to the wheels



Objectives:

- Reduce weight as much as possible
- Reduce size to accommodate for the new 10 inch rims
- Gear box life time of ~100 hours
- Sizing wheel-assembly from steering and suspension needs

In-wheel Motor - First Design

Design and Optimization of an in-wheel powertrain system

Project divided into 2 simultaneous parts:

- Gear box Design & opti
- Mechanical Integration

1) Gear Box:

- Literature study of the system (gear ratio, gear calculation)
- First iteration
- Implementation on software KissSys (with carrier, shaft, bearings)
- Validation of the design thanks to kissSys
- Continue iterations to get the optimal gear box (trade off between lifetime and efficiency)



Compound Planetary Gear-Box -
First Design

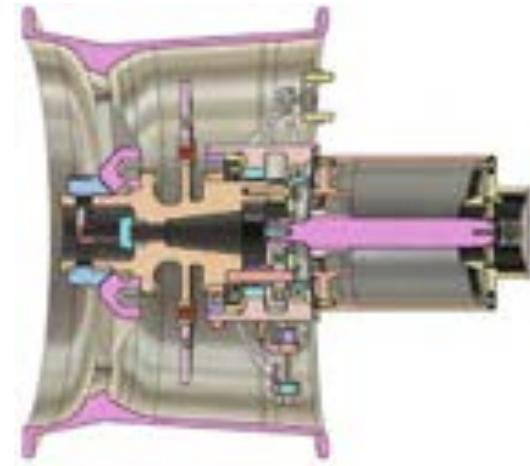
Design and Optimization of an in-wheel powertrain system

Project divided into 2 simultaneous parts:

- Gear box Design & opti
- Mechanical Integration

2) Mechanical integration

- Direct integration of gear box:
 - carrier, shaft, planet bearings
- Hard work on lubrication and oil sealing
- Design of wheel hub and upright (metal 3D printing?)
- Choice of hub's bearing



Cross section view of an *in-wheel* motor wheel assembly

Design and Optimization of an in-wheel powertrain system



Objective of the project for the end of the semester :

- full design ready to implement in september 2022
- List of materials to be purchased
- cost prediction

→ Need 3 people for this project

Associated tasks :

- literature study
- comparison of various solutions
- CAD/FEM
- Gears simulation on software KissSys
- topology optimization



Project Presentation

Aerodynamics - Rear Wing Design

09/12/2021



Rear Wing Design

Function:

- Provide Downforce to the car

Objectives:

- Optimize the Lift/Drag ratio
- Make it as light as possible
- Design handy fixations



Mercury's Rear Wing

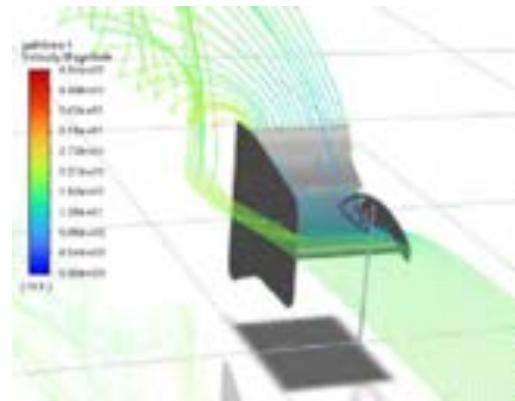
Rear Wing Design

Objective of the project for the end of the semester :

- Full design of the new wing and Endplates
- Determination of optimal composite layup
- Full design of the fixations

Associated tasks :

- literature study of the system
- comparison of various solutions
- CAD
- CFD simulations
- FEM simulations



Project Presentation

Aerodynamics - Front Wing Design

09/12/2021



Front Wing Design

Function:

- Provide Downforce to the car



Objectives:

- Optimize the Lift/Drag ratio
- Make it as light as possible
- Design handy fixations

Mercury's Front Wing

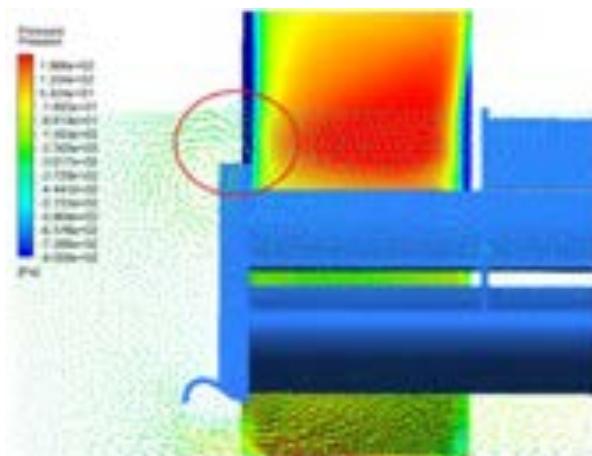
Front Wing Design

Objective of the project for the end of the semester :

- Full design of the new wing and Endplates
- Determination of optimal composite layup
- Full design of the fixations

Associated tasks :

- literature study of the system
- comparison of various solutions
- CAD
- CFD simulations
- FEM simulations



Suspension Design adapted for in-wheel motor

VD

09/12/2021



Suspension Design adapted for in-wheel motors

Function:

- Create the optimal link between the chassis on the track

Objectives:

- Geometry adapted to in-wheel motors
- Determine all optimal suspension parameters:
 - Springs coefficient
 - Damping coefficient
 - Suspension linking points on chassis and wheel assembly
- Make a new front anti-roll bar adapted to the geometry



Design and Optimization of an in-wheel powertrain system



Objective of the project for the end of the semester :

- full design ready to implement in september 2022
- List of materials to be purchased
- cost prediction
- Hard work on final report : engineer approach, useful for next generation in Racing Team

→ Need 3 people for this project

Associated tasks :

- literature study
- comparison of various solutions
- Hard work on suspension & Vehicle Dynamics Theory
- Suspension simulation on software OptimumKinematics
- CAD/FEM
- Matlab codes

K – Lab LNET

- 1. Design a miniature controlled humidity chamber for Hydrovoltaic device**
- 2. Design of a thermal stage for thermally tunable metasurfaces**
- 3. a) Build an experimental setup for free convection in array of parallel plate channels. b) Demonstrating different boiling regime**



Prof. Giulia Tagliabue



3 Groups with 3-4 students each

1. Miniature controlled humidity chamber for hydrovoltaic device



Evaporation-induced potential

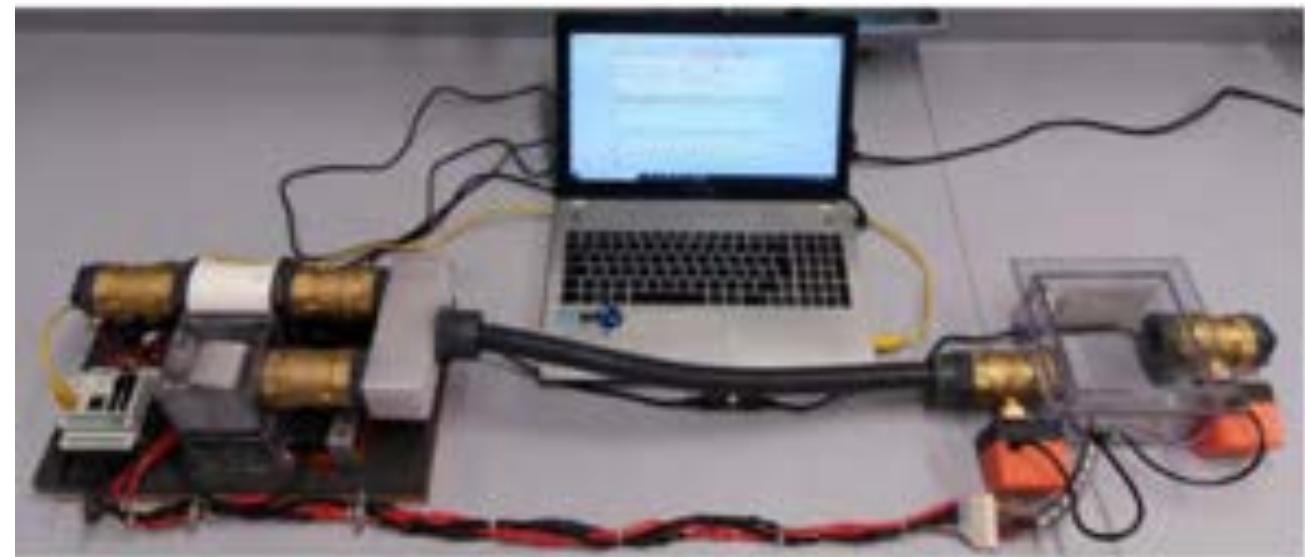
Environmental parameters

- Relative humidity
- Temperature
- Evaporation rate
- ...



Devices' efficiency and output power

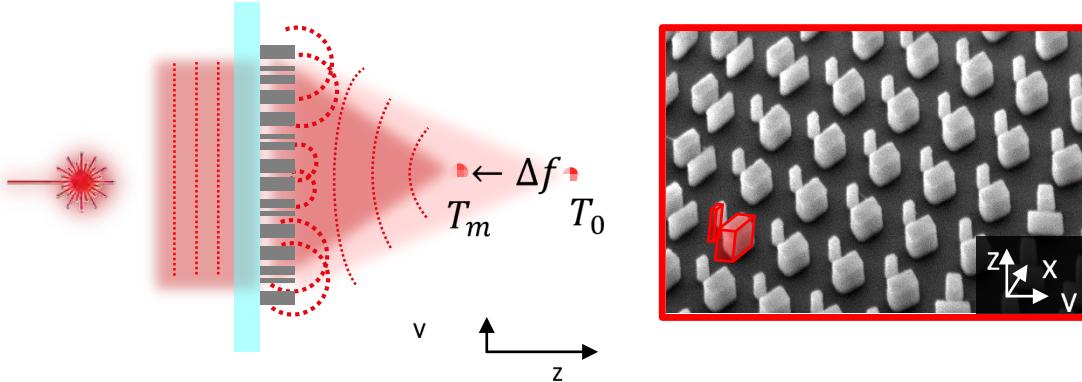
Current humidity chamber 15cm X 15cm X 10cm



The main objectives of the project

1. Miniaturize the chamber, such that it can be used under a Microscope
2. Improve the dehumidification system
3. Controlling the temperature uniformly inside the miniature chamber

2. Design of a thermal stage for thermally tunable metasurfaces



2D arrangements of meta-atoms with sub-wavelength spacing to precisely control and manipulate the properties of a light beam.

Background

Metasurfaces are used to produce flat versions of traditional optics with tunability.

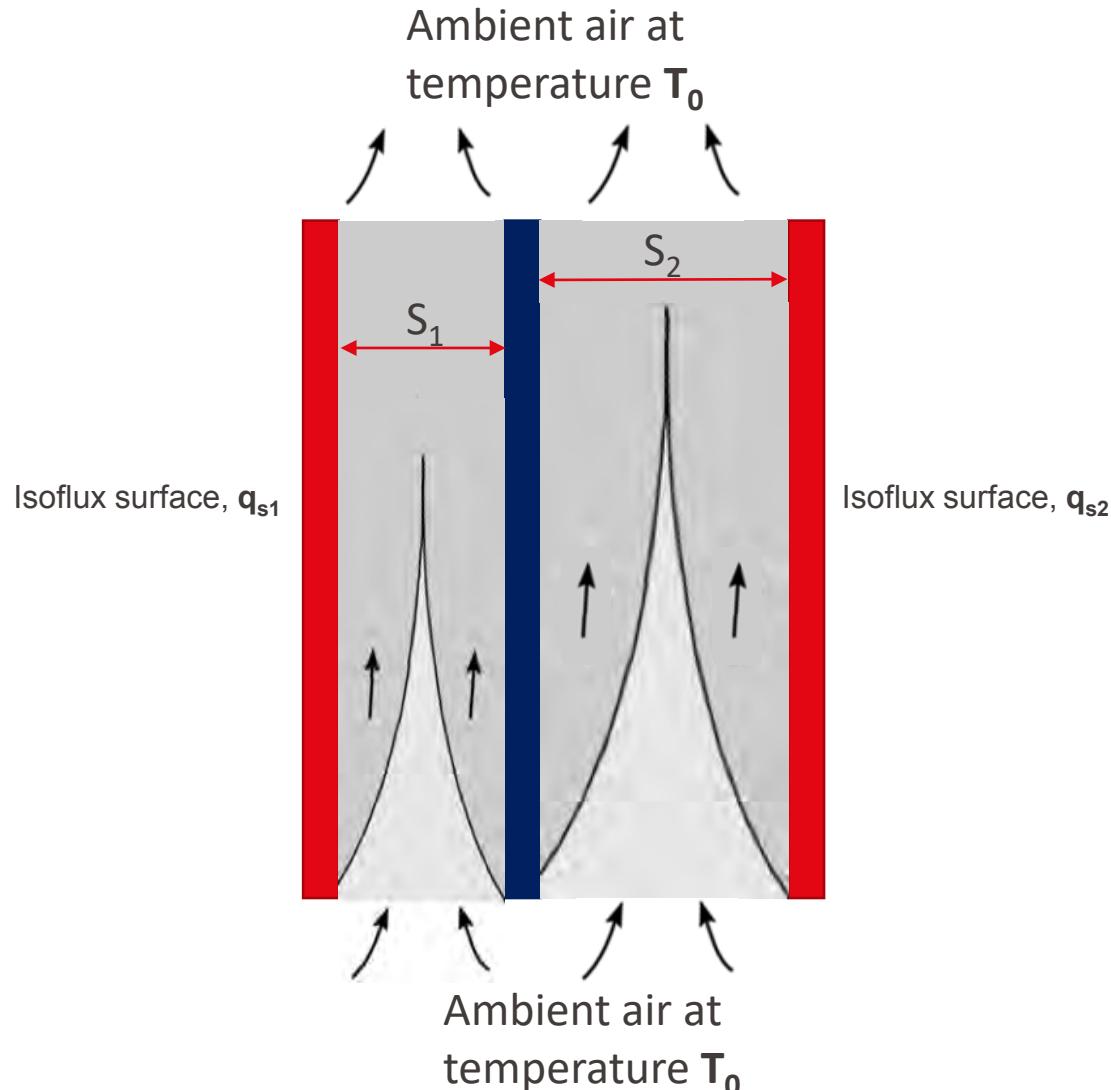
The aim of this project is to design and fabricate a thermal stage to test thermally tunable metasurfaces.

The main objectives of the project

Design of a thermal stage with the following properties:

1. Capable of reaching high temperature (>200 °C)
2. Temperature feedback
3. Adjustable mounting system for the optics/metasurfaces
4. Optically transparent

3.a. Build an experimental setup for free convection in array of parallel plate channels



Background

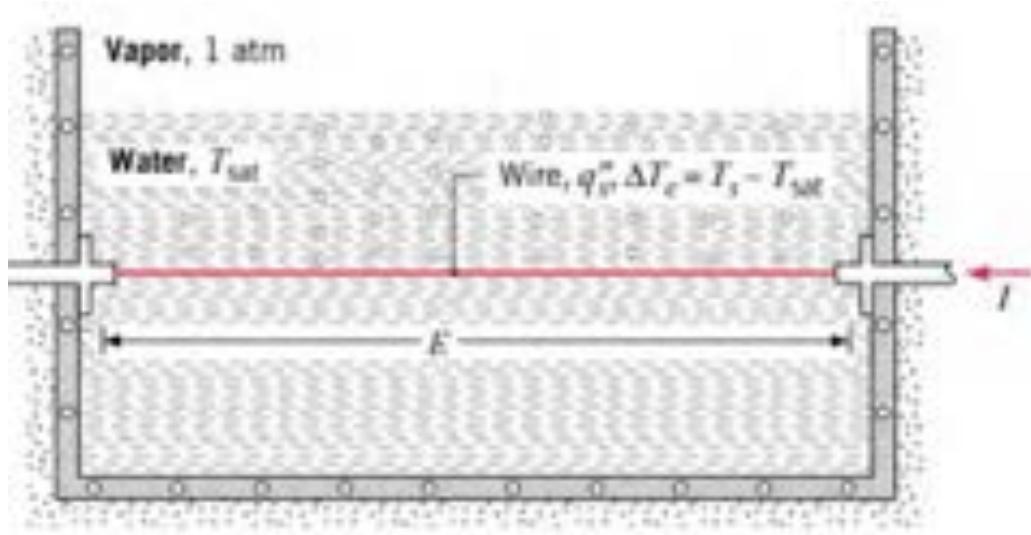
The theory will be covered by Prof. Tagliabue in the heat transfer course next semester.

The heat transfer rates can be altered by adjusting the spacing(S_1, S_2) between the plates or ratio of length and spacing.

The main objectives of the project

1. Do the structure and thermal design of the setup.
2. Obtain the correlation for heat transfer coefficient in two-plate configuration.
3. Repeating part 1 in three-plate configuration (with and without heat flux).
4. Optimal spacing that maximizes the heat transfer rate.
5. Is vertical plates best in every scenarios?

3.b Demonstrating different boiling regime



Nukiyama's power controlled heating setup for demonstrating the boiling curve

Background

By controlling current under a voltage difference, heat flux was supplied and temperature was determined by the change in resistance of the wire. By having a wide range of heat flux different boiling regime can be visualized.

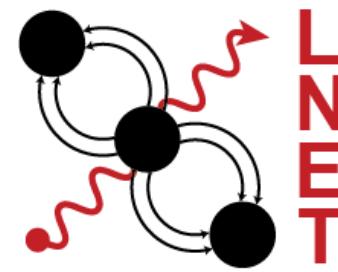
The main objectives of the project

1. Build a similar setup as Nukiyama's to show all the boiling regime in the boiling curve
2. Study the change in boiling curve at different pressures
3. Effect of ambient environment, such as having a pure vapor chamber instead of air.

Thank you!

Feel free to contact for more information about the project.

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